

END STAGE EXPERIMENT
Flight Pattern Descriptions

Experiment/Module: Tropical Cyclones at Landfall

Investigators: John Kaplan, Peter Dodge, Ghassan Alaka, Heather Holbach, Jun Zhang, Frank Marks

University mobile observing team leaders:

Michael Biggerstaff, University of Oklahoma
John Schroeder, Texas Tech University
Forrest Masters, University of Florida
Kevin Knupp, University of Alabama at Huntsville
David Nolan, University of Miami

Requirements: TC making landfall, approaching the coastline, undergoing rapid weakening, or extratropical transition

End Stage Science Objectives Addressed:

- 1) Collect observations targeted at better understanding changes TCs undergo at landfall. Objectives include validation of surface wind speed estimates and model forecasts, understanding factors that modulate intensity changes near and after landfall, and to understand processes that lead to tornadoes in outer rainbands [*IFEX Goals 1, 3*]
- 2) Test new (or improved) technologies with the potential to fill gaps, both spatially and temporally, in the existing suite of airborne measurements in landfalling TCs. These measurements include improved three-dimensional representation of the TC wind field, more spatially dense thermodynamic sampling of the boundary layer, and more accurate measurements of ocean surface winds [*IFEX Goal 2*].

P-3 Pattern #1: Landfall (Offshore Intense Convection)

What to Target: An intense rain band > 150 n mi (280 km) from the center of either a tropical storm or hurricane that is forecast to make landfall along the U.S coastline

When to Target: This module should be performed within ~12–24 h of the time of landfall

Pattern: Break-away/non-standard (see Fig. EN-1 and description below):

Fig. EN-1 shows a sample Offshore Intense Convection flight pattern near the Carolina coast. The P-3 should cross the target band 10-15 n mi (20–25 km) downwind of the intense convective cells and then proceed to 15 n mi (25 km) outside the rain band axis. The aircraft then turns upwind and proceeds along a straight track parallel to the band axis. When the P-3 is 10-15 n mi (20–25 km) upwind of the target cells, the aircraft turns and proceeds along a track orthogonal to the band axis until the P-3 is 15 n mi (25 km) inside the rain band then turns downwind and flies parallel to the rain band axis.

END STAGE EXPERIMENT
Flight Pattern Descriptions

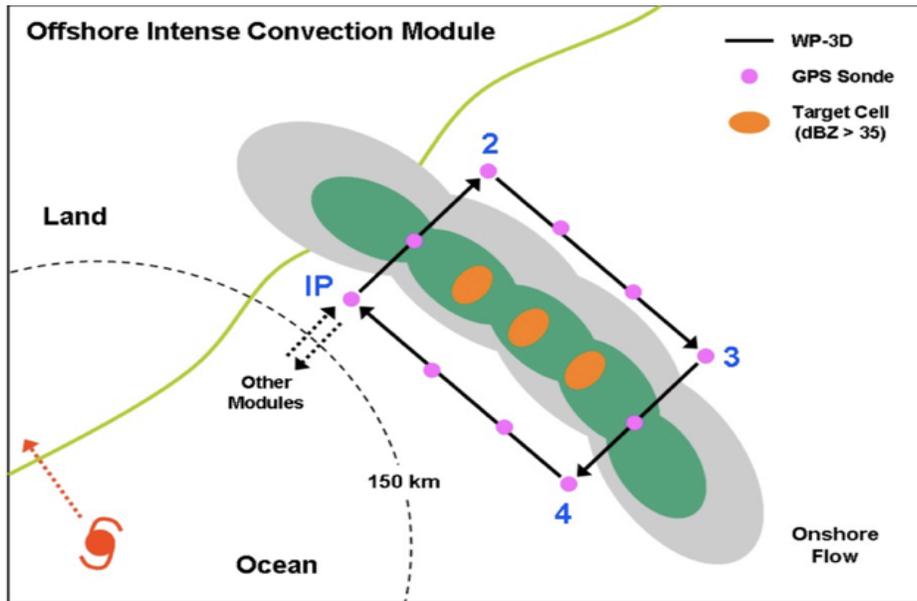


Figure EN-1. Offshore Intense convection module

Flight altitude: 10 kft or higher

Leg lengths: ≥ 40 n mi (75 km) for each parallel leg

Estimated in-pattern flight duration: 1–2 h

Expendable distribution: Deploy dropwindsondes at the start or end points of each leg, at the band axis crossing points, and at 10-15 n mi (20–25 km) intervals along each leg parallel to the band. At least 2 dropwindsondes should be deployed on either side of the convection and at least 1 dropwindsonde should be deployed each time the band-axis is crossed (for a minimum of 6 dropwindsondes).

Instrumentation Notes: The Tail Doppler radar should be turned on and scanning normally. The Lower Fuselage radar (MMR) should operate in HWX mode to collect both reflectivity and Doppler velocity. Aircraft should avoid penetration of intense reflectivity regions (particularly over land).

P-3 Pattern #2: Landfall (Coastal Survey)

What to Target: A tropical storm or hurricane that is forecast to make landfall along the U.S coastline

When to Target: This module should be performed within ~6–12 h of the time of landfall

Pattern: Break-away/non-standard (see Fig. EN-2 below and description below):

END STAGE EXPERIMENT
Flight Pattern Descriptions

Fig. EN-2 shows a sample Coastal Survey pattern for a hurricane landfall near Melbourne, Florida. The P-3 would fly parallel but ~5-8 n mi (10–15 km) offshore so that the SFMR footprint is out of the surf zone. The second pass should be parallel and as close to the coast as safety permits. Finally, a short leg would be flown from the coast spiraling towards the storm center. If mobile radars and other mobile surface observing teams are deployed then legs should be adjusted so airborne radar data and sondes can be released in the surface dual Doppler lobes.

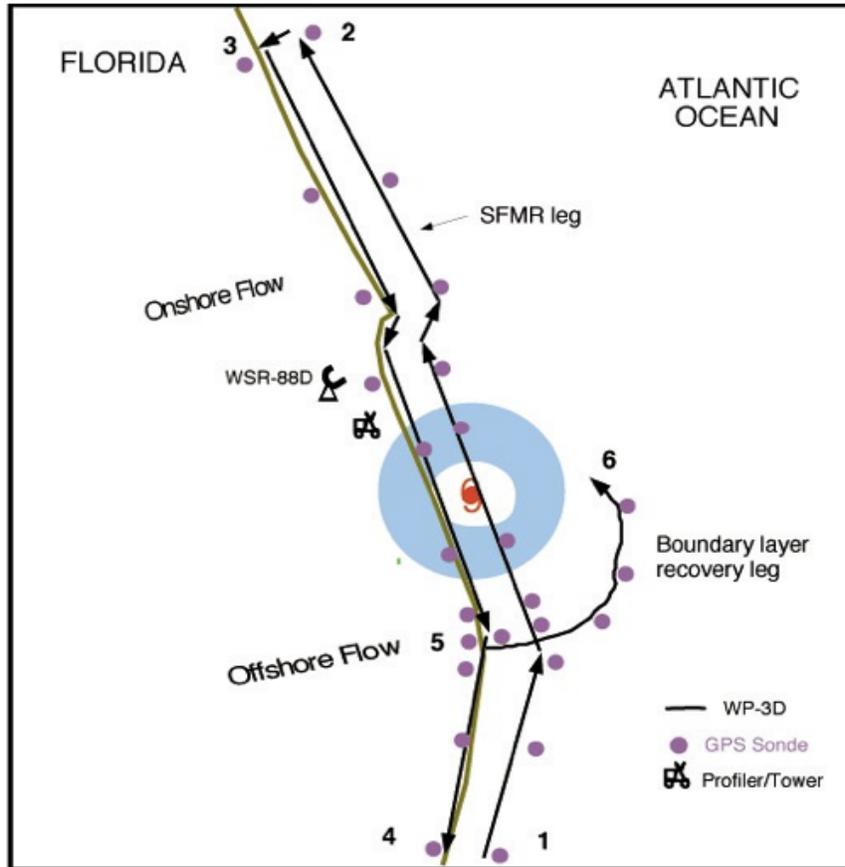


Figure EN-2. Coastal Survey module

Flight altitude: ~5 kft for first pass and then climb to slightly higher altitude (~7.5 kft) if needed for second pass.

Leg lengths: ~80 n mi (150 km)

Estimated in-pattern flight duration: ~2 h

Expendable distribution: Dropwindsondes at RMW and at 7, 14, 27, 41 and 54 n mi (12.5, 25, 50, 75, 100 km) from the RMW on either side of storm in both the near shore and offshore legs that are to be flown parallel to the shoreline. If surface towers or portable mesonet stations are present adjust drops to be upwind of the surface sites. Dropwindsondes should be deployed quickly at start of outbound leg between near shore and offshore parallel legs and then every 5-8 n mi (10–15 km) thereafter.

END STAGE EXPERIMENT
Flight Pattern Descriptions

Instrumentation Notes: The Tail Doppler radar should be turned on and scanning normally. The Lower Fuselage radar (MMR) should be in HWX mode if conditions permit. Aircraft should avoid penetration of intense reflectivity regions (particularly those overland).

P-3 Pattern #3: Landfall (Real-time)

What to Target: A hurricane that is forecast to make landfall along the U.S coastline

When to Target: This module should be performed within ~6–12 h of the time of landfall

Pattern: Break-away/non-standard (see Fig. EN-3 and description below):

Fig. EN-3 shows a sample Real-time module flight pattern. The P-3 descends at the initial point and begins a low-level Figure-4 pattern, possibly modifying the legs to fly over buoy or C-MAN sites if possible. If mobile surface teams are deployed near the coast the pattern can be rotated such that the near coastal downwind legs intersect with the mobile radar dual Doppler lobes. If time permits, the P-3 would make one more pass through the eye.

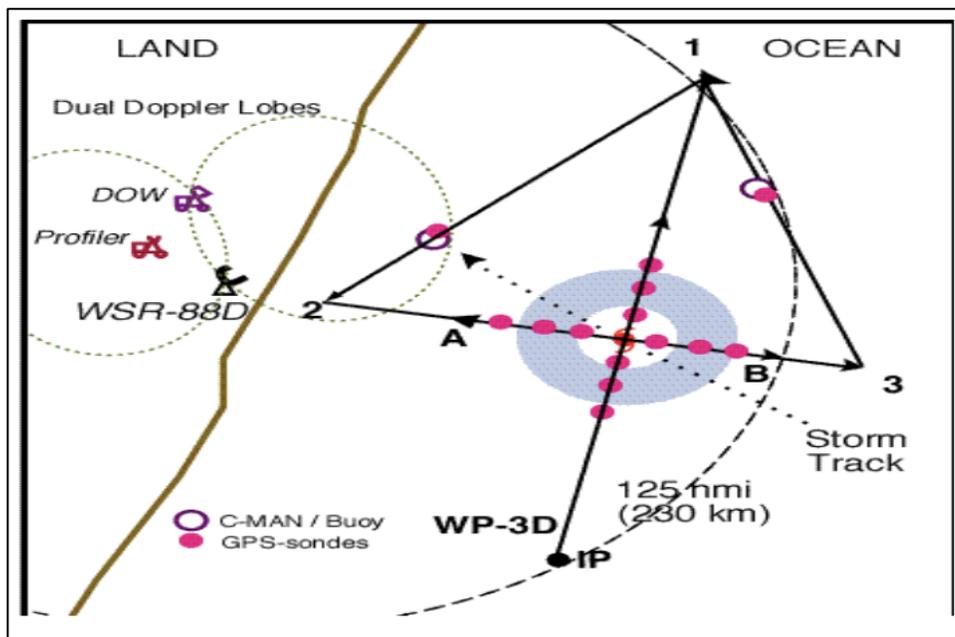


Figure EN-3. Real-time module

Flight altitude: Below 5,000 ft (1.5 km) (or the lowest level deemed to be safe by flight personnel)

Leg lengths: ~100 nm (185 km)

Estimated in-pattern flight duration: ~2–3 h

END STAGE EXPERIMENT
Flight Pattern Descriptions

Expendable distribution: Dropwindsondes should be released near buoys or C-MAN sites (if possible) and at or just inside the flight-level RM. If portable wind towers or mesonet stations are present near the coast, then dropwindsondes should be dropped upwind of those positions on the near coastal leg.

Instrumentation Notes: The Tail Doppler radar should be turned on and scanning normally. The Lower Fuselage radar (MMR) should operate in HWX mode if conditions permit. Also, it is essential that these passes be flown as straight as possible, because turns to fix the eye will degrade the Doppler radar coverage.

P-3 Pattern #4: Landfall (SFMR Coastal)

What to Target: A tropical storm or hurricane that is forecast to make landfall in a region with varying bathymetry near the coastline

When to Target: This module should be performed when sustained winds are greater than 30 kt in the region of interest

Pattern: Break-away/non-standard (see Fig. EN-4 and description below):

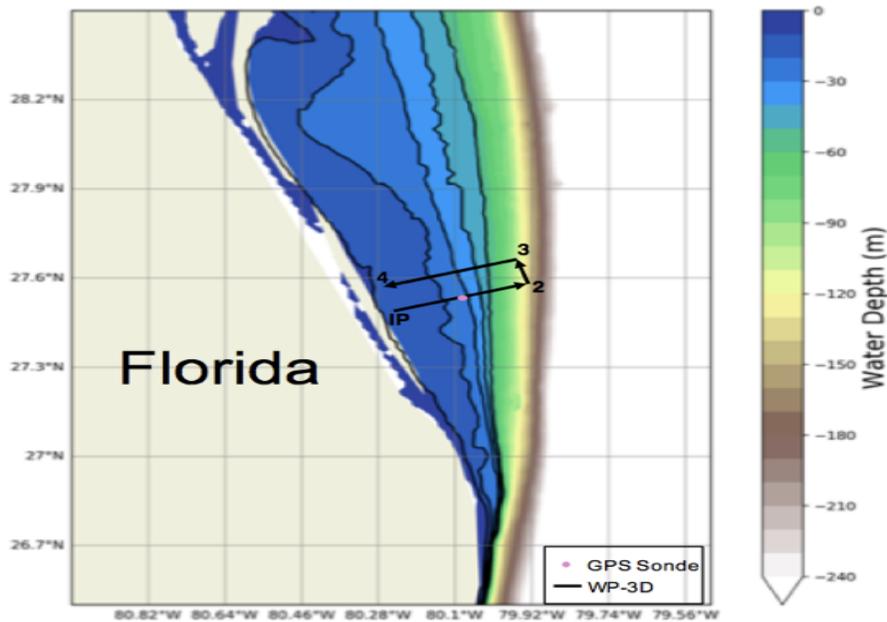


Figure EN-4. SFMR coastal module

The P-3 would fly perpendicular to the coastline, across the bathymetry gradient, in a region with near constant surface winds. After flying away from the coast for about 27 n mi (50 km), the P-3 would turn downwind and then back towards the coast repeating a similar line as the first leg.

2020 NOAA/AOML/HRD Hurricane Field Program - IFEX

END STAGE EXPERIMENT *Flight Pattern Descriptions*

Flight altitude: Can be performed at any altitude between 5 kft to 12 kft. Aircraft should maintain a constant altitude throughout the module.

Leg lengths: ~13-27 n mi (25–50 km)

Estimated in-pattern flight duration: ~30–45 min

Expendable distribution: Dropwindsonde at middle of first leg. If winds appear to vary over the leg then an additional dropwindsonde may be necessary.

Instrumentation Notes: SFMR should be operating normally. Tail and Lower fuselage radars should also be operated normally, with the lower fuselage (MMR) in HWX mode if conditions permit.