

Evaluating the Impact of Hurricane Observations from the Unmanned Coyote Aircraft in Observing System Simulation Experiments

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NOAA Hurricane Forecast Improvement Project (HFIP)



Coyote Unmanned Aircraft System

A New Tool to Better Observe Tropical Cyclones



The NOAA P-3 Aircraft Typically Penetrates Tropical Cyclones and Collects Data with a Suite of Instruments

The Dropsonde System is Designed to Measure the Vertical Variations in the Atmosphere



The Coyote is a Small Aircraft that Uses the Dropsonde Deployment System and Sensor Suite and is Capable of Remaining Airborne for ~1 h or Longer

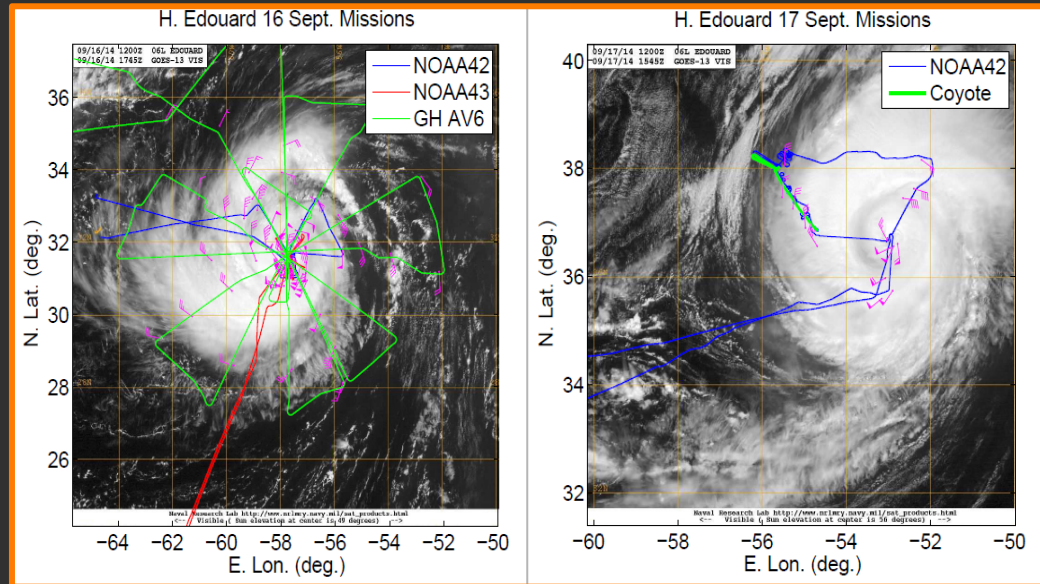
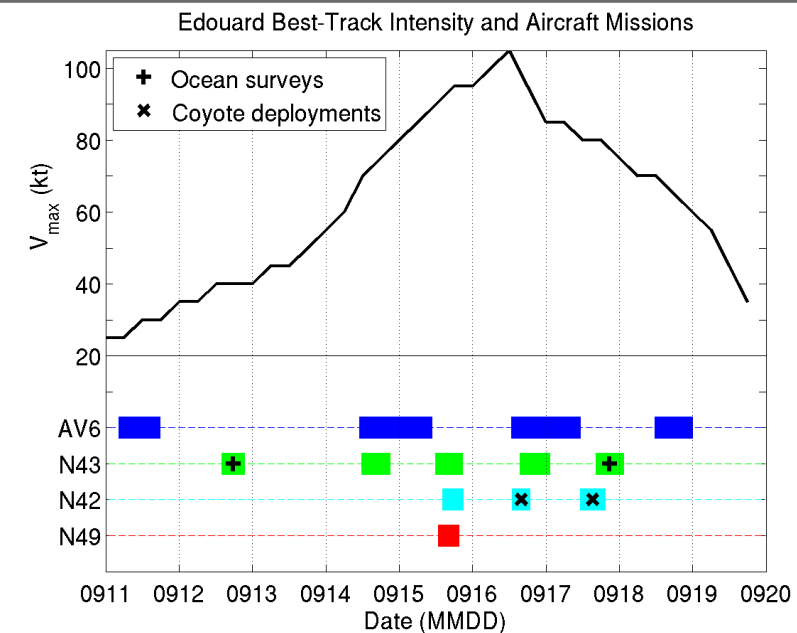


Hurricane Edouard (2014) Aircraft Missions

Coordination of Multiple Aircraft and Coyote Missions

Multiple Aircraft Conducted Successful Missions:

- NASA Global Hawk (AV6)
- NOAA P-3 (N42/N43) and G-IV (N49)
- Ocean Surveys (+)
- Coyote UAS Missions (x)



1

16 September 2014 1432Z
 Eye/Eyewall Sampling
 28-minute Mission
 Min. Altitude 896 m
 Max. Wind Speed 100 kt

2

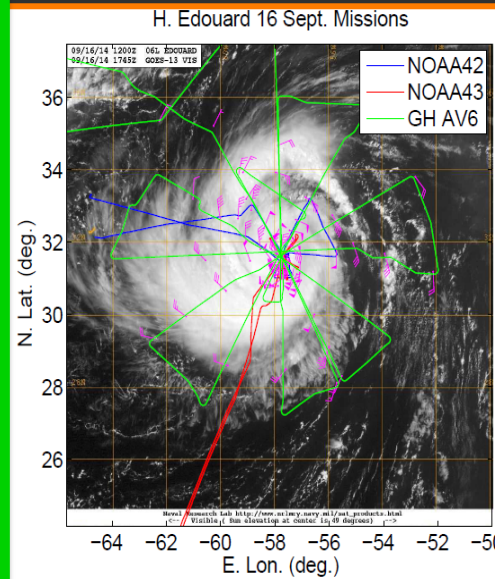
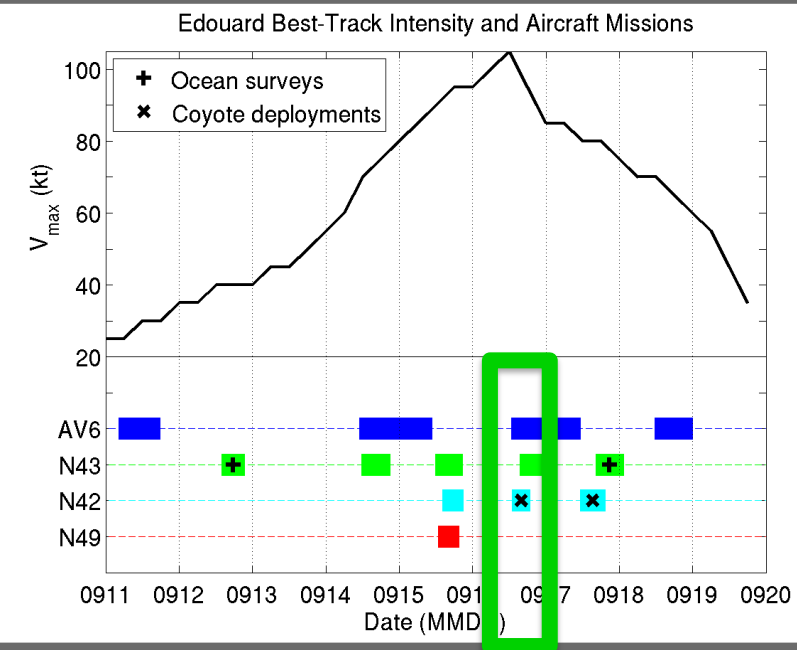
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 Inflow Channel Sampling
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 Min. Altitude 400 m
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Hurricane Edouard (2014) Aircraft Missions

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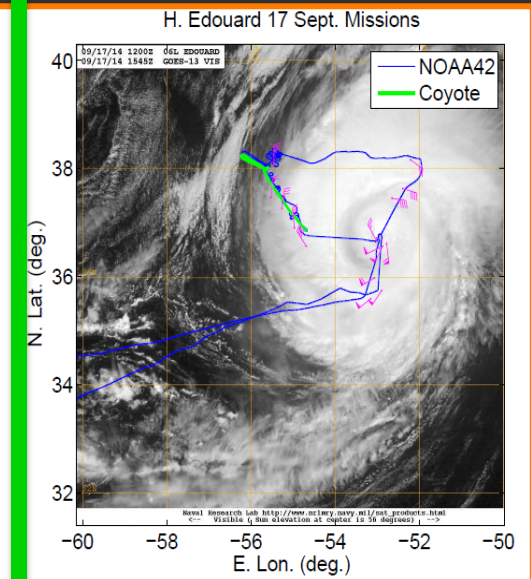
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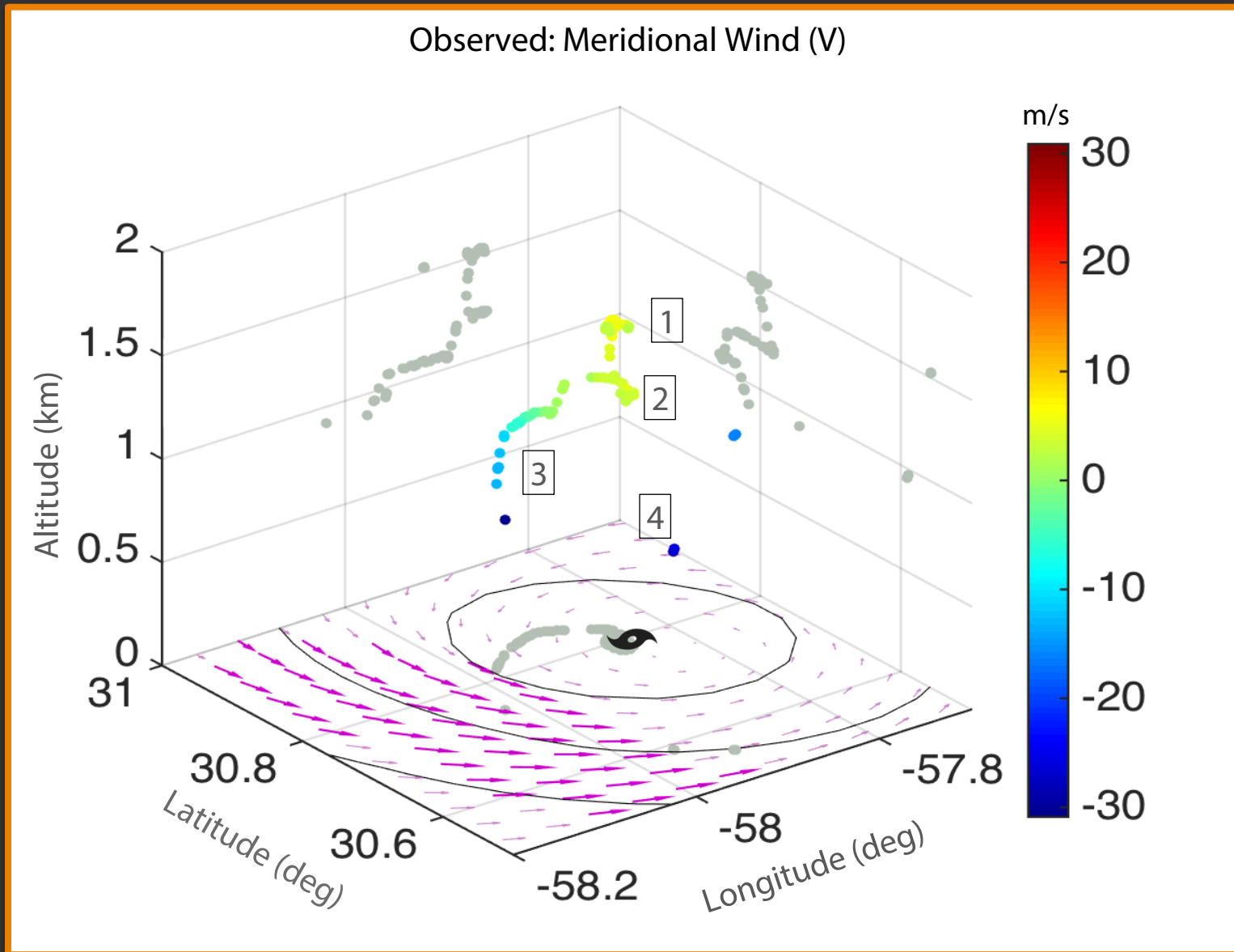
2

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Can we repeat the findings of the real-data experiment and expand on it in an OSSE?

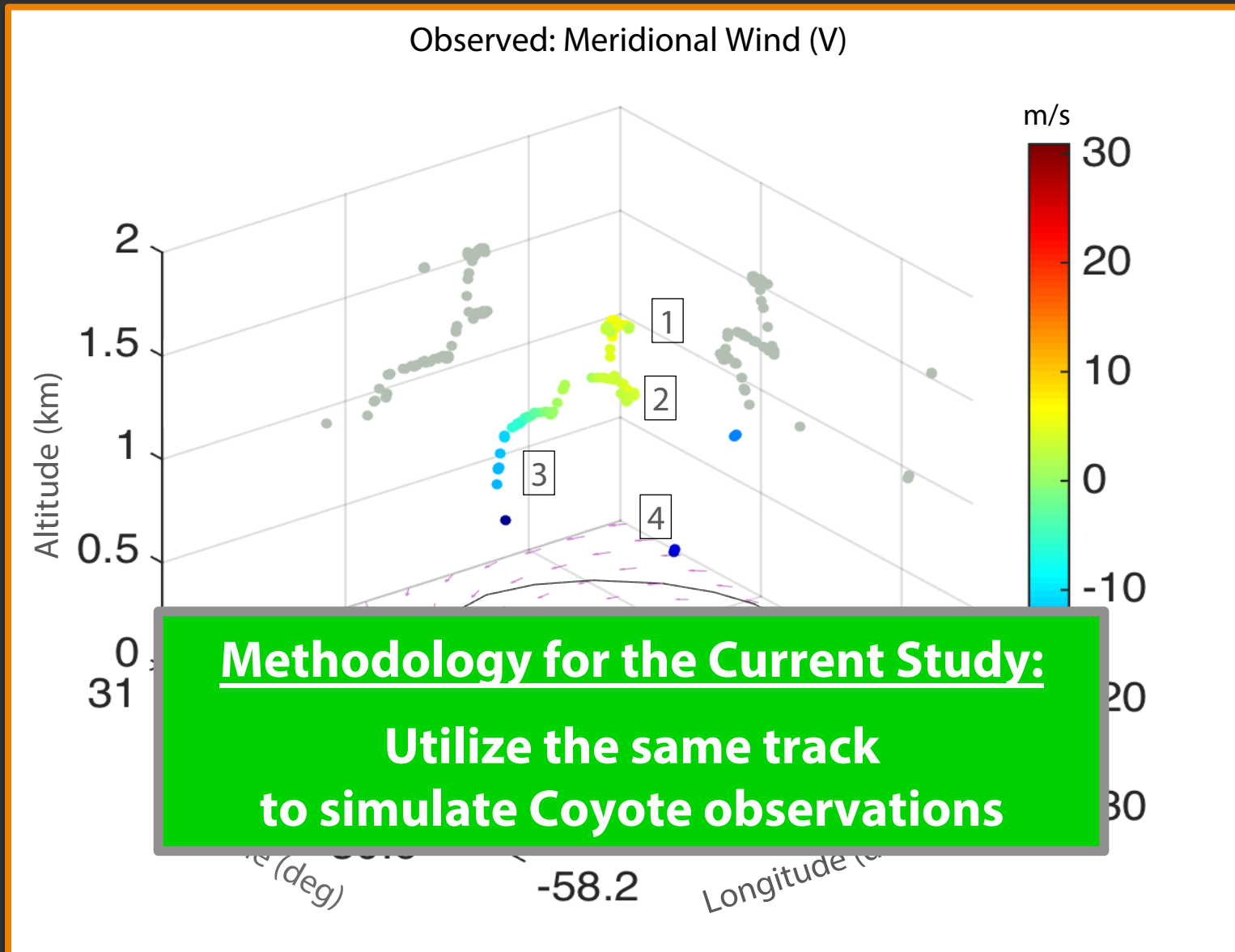
Coyote Mission on 16 September

Closer Look at What Was Observed



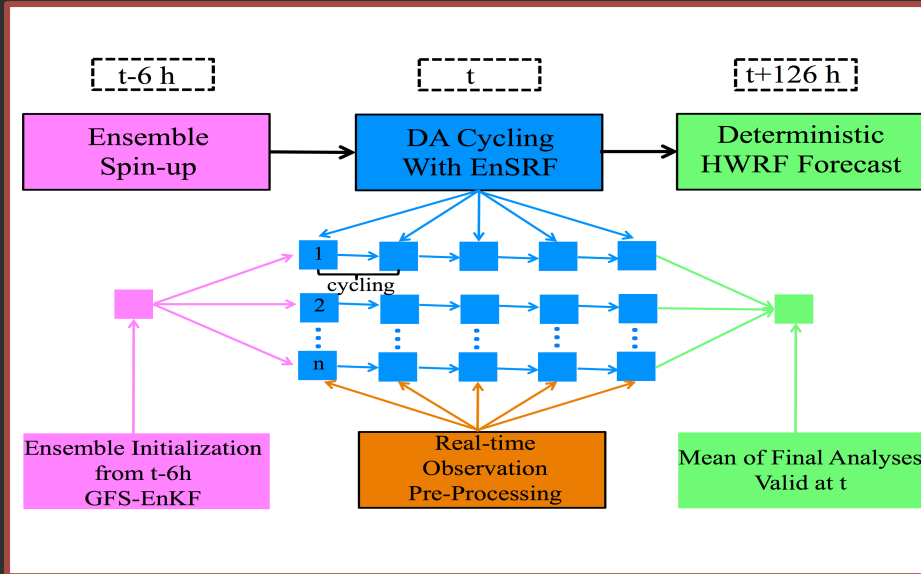
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Closer Look at What Was Observed



OSSE Experimental Setup

Data Assimilation System and Nature Run

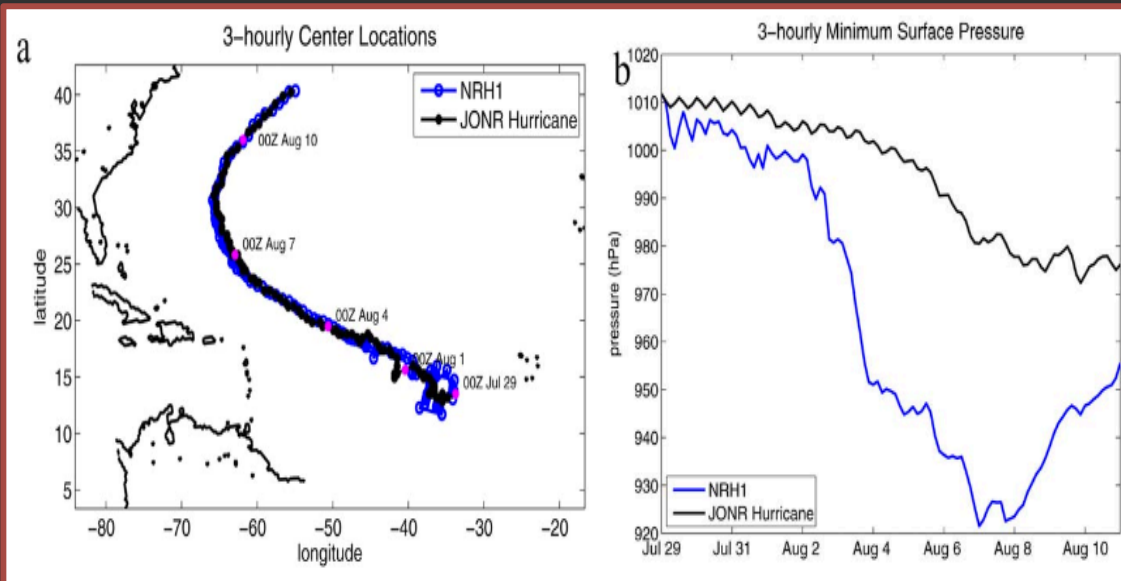


HEDAS Characteristics

- Focus on tropical cyclone inner-core data assimilation for high-resolution vortex initialization
- Uses the ensemble square-root Kalman filter (Whitaker and Hamill 2002)
- Storm-relative observation processing capability (Aksoy 2013)

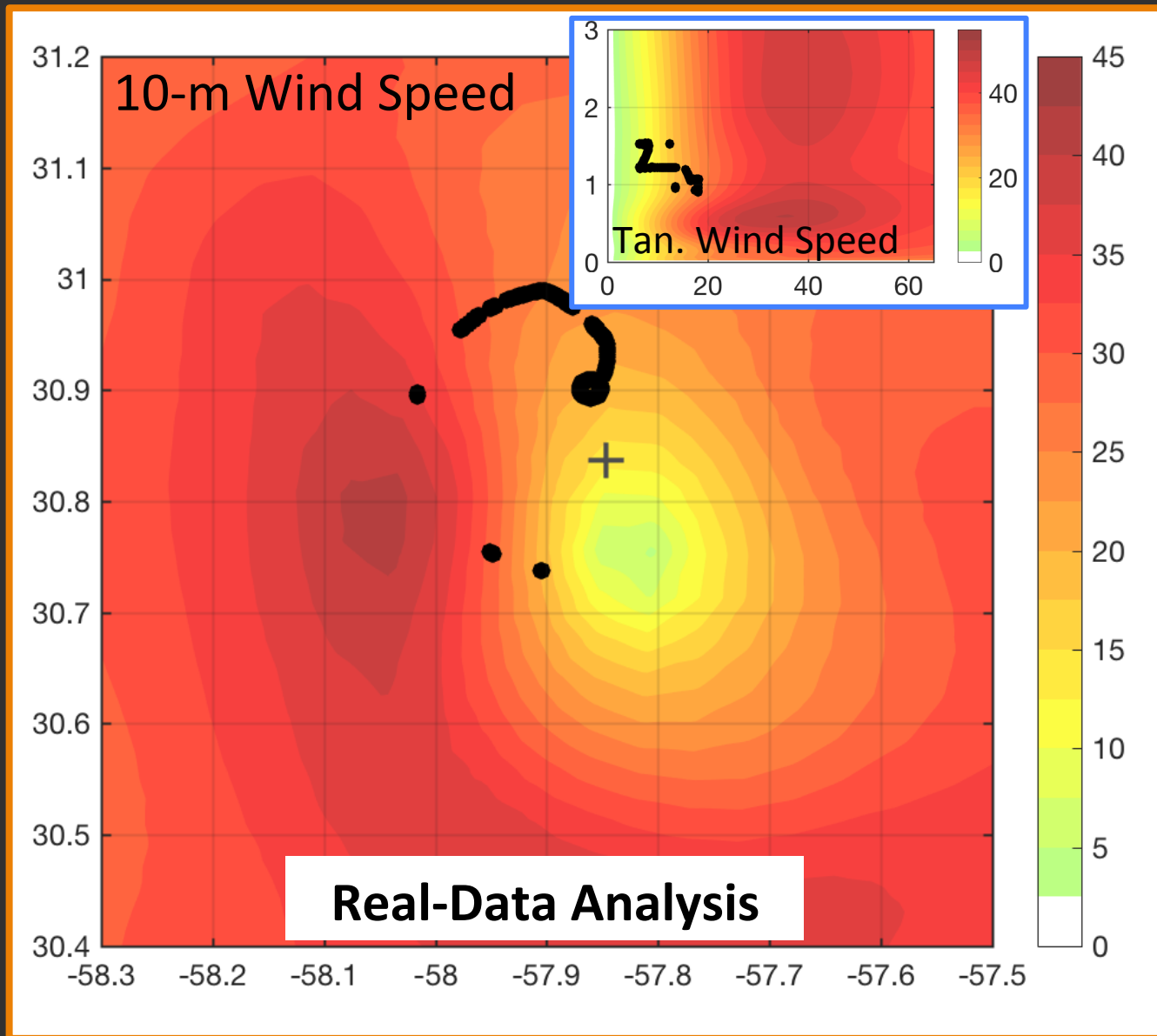
Nature Run Characteristics

- From Nolan et al. (JAMES 2013)
- High-resolution (27/9/3/1 km) hurricane simulation with WRF-ARW
- Embedded in and nudged toward an ECMWF T511 nature run



Simulating Coyote Observations for OSSEs

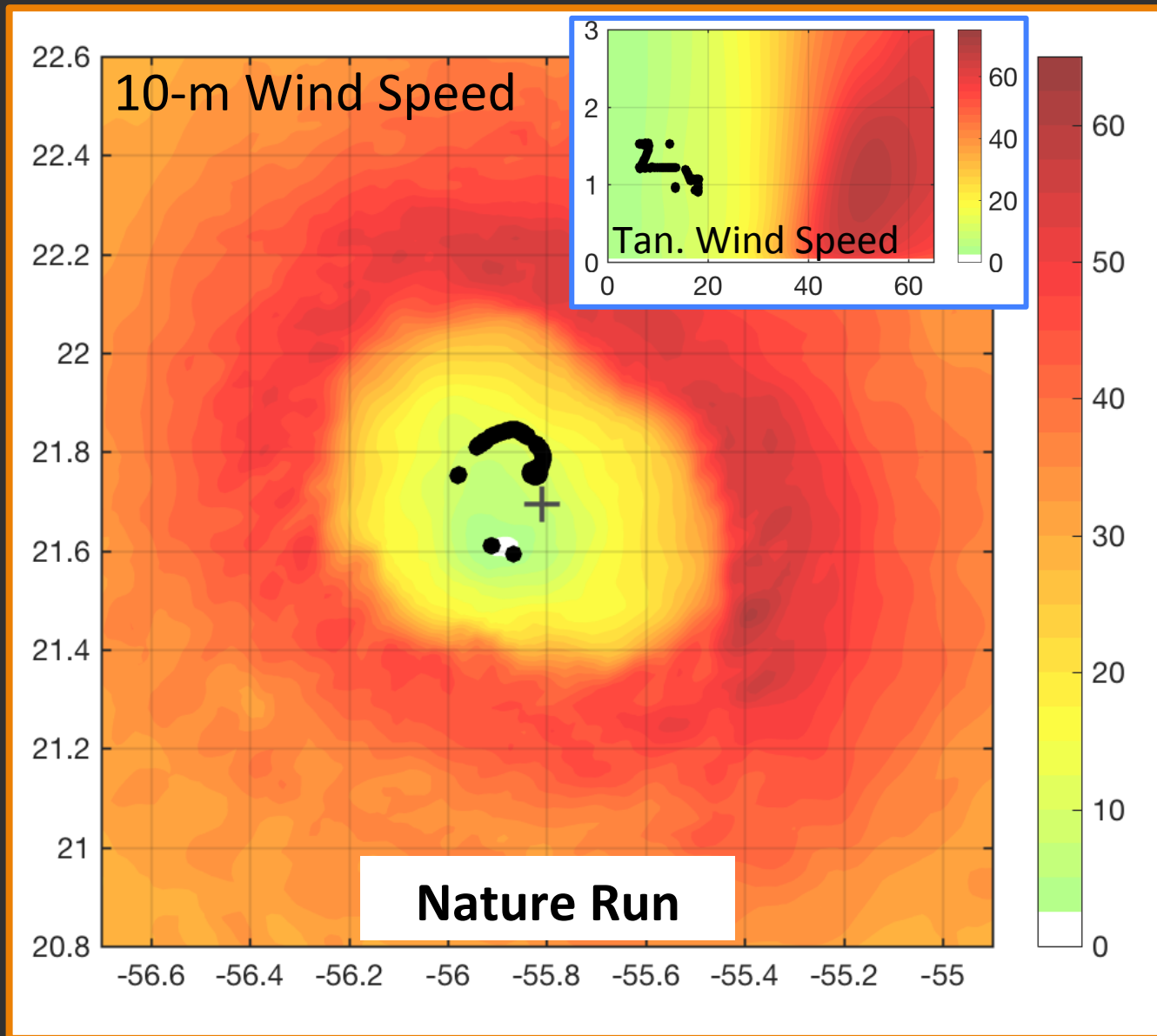
Question: What If We Observed the Nature Run Same As Real Data?



Actual Edouard (2014)
16 September
Observations

Simulating Coyote Observations for OSSEs

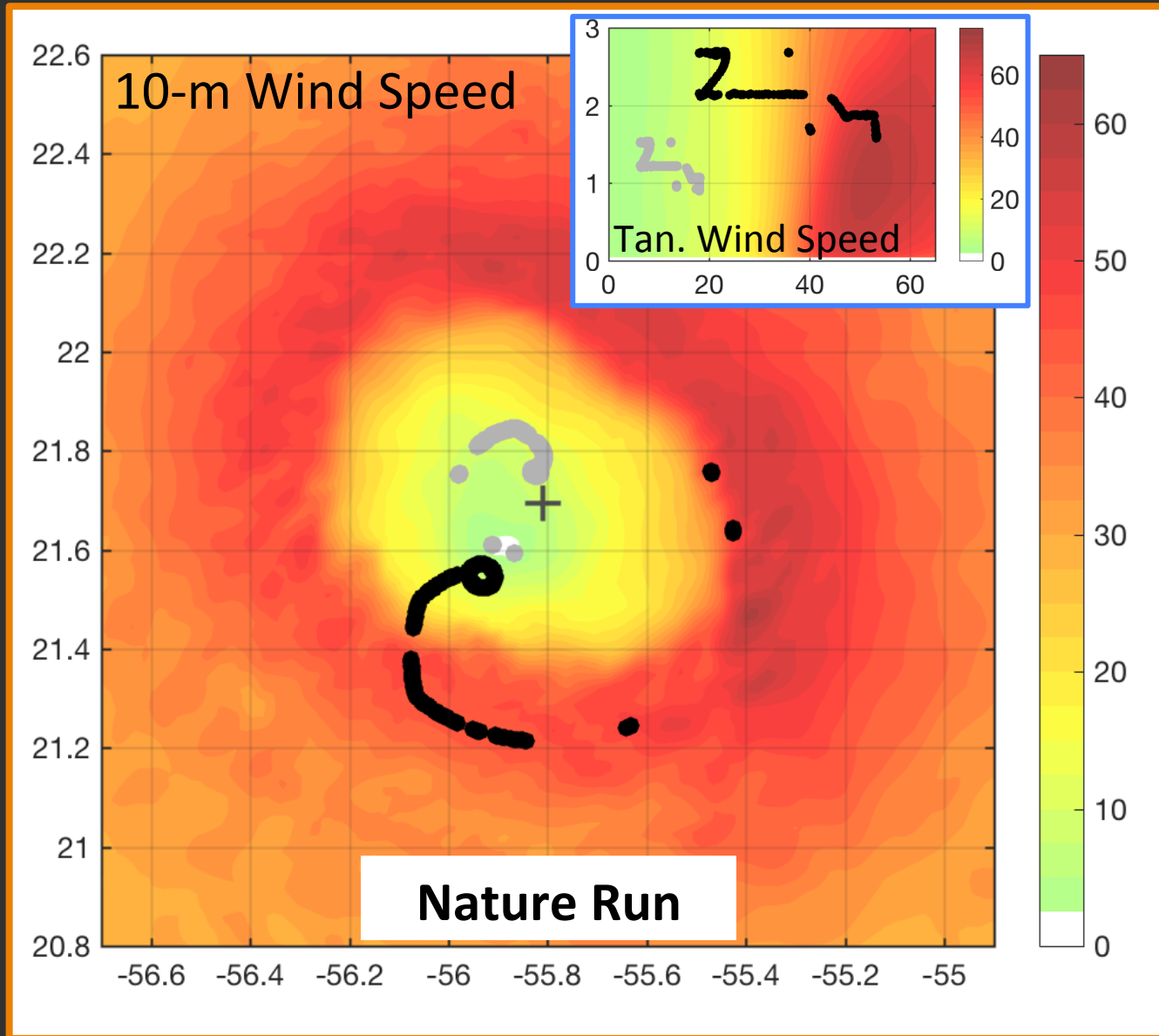
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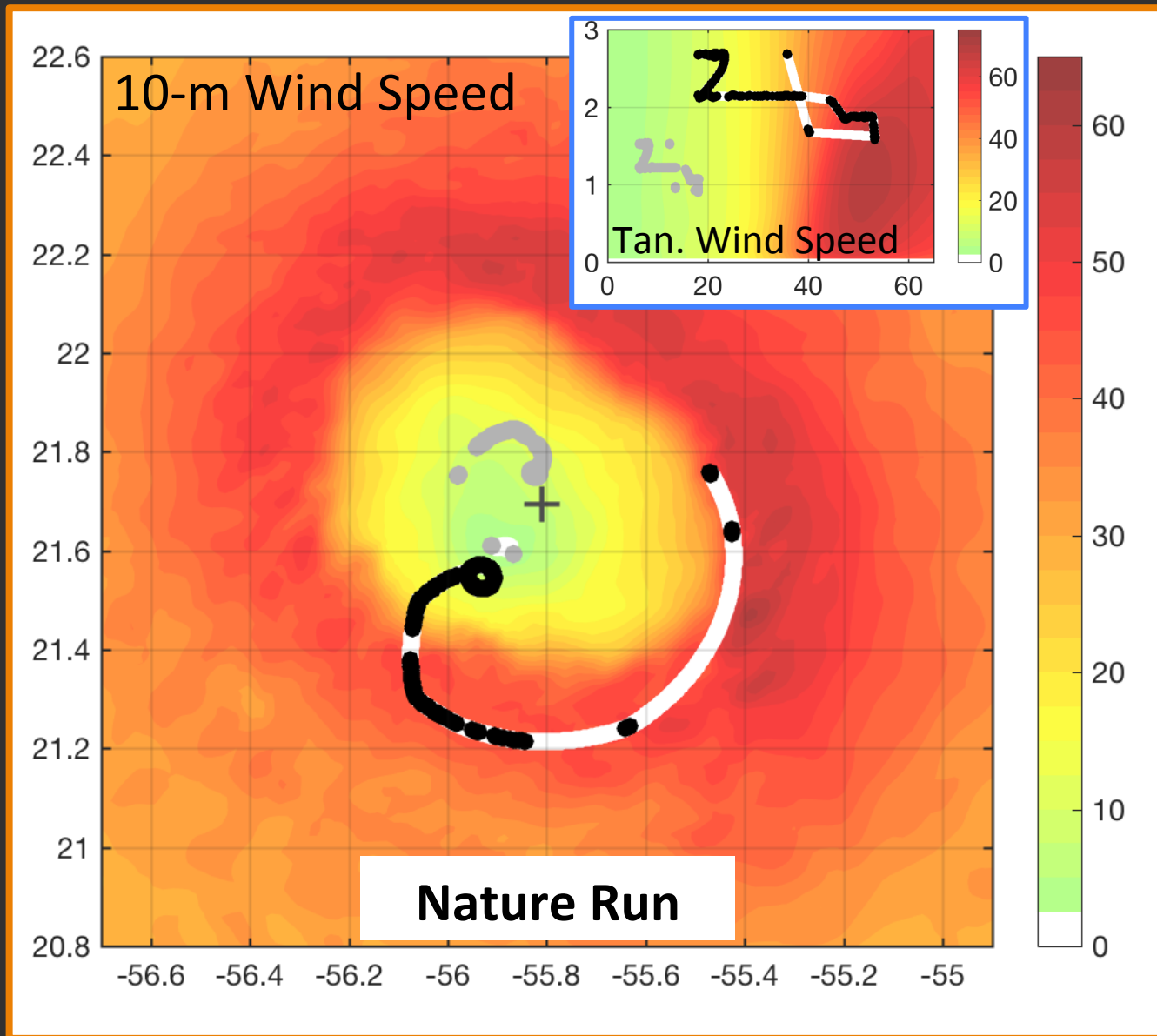


Actual Edouard (2014)
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Observations

1 Observations
Rotated & Expanded
to Match Nature Run

Simulating Coyote Observations for OSSEs

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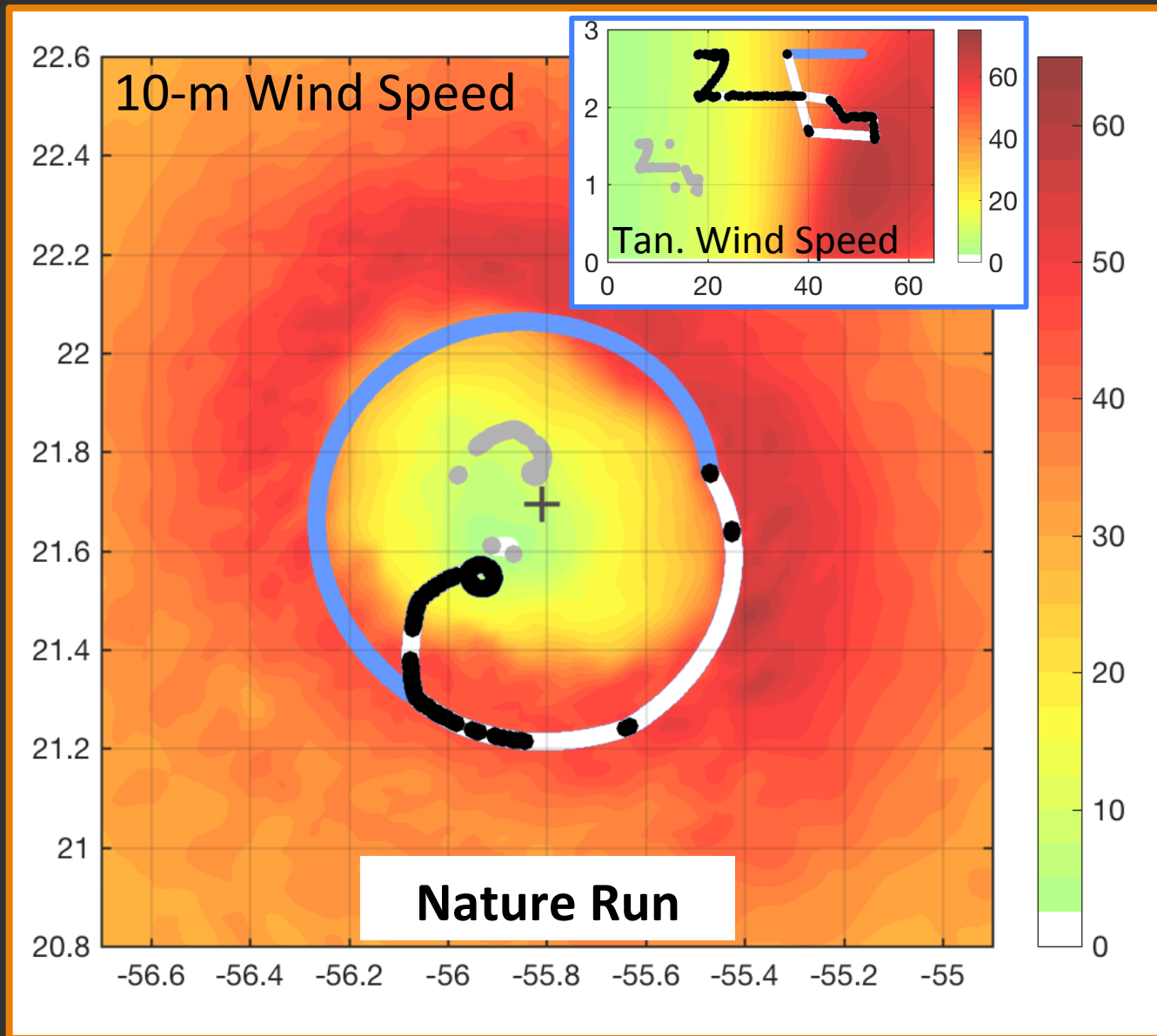
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1 Observations
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2 Observations
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to Fill In Gaps

Simulating Coyote Observations for OSSEs

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Actual Edouard (2014)
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Observations

1 Observations
Rotated & Expanded
to Match Nature Run

2 Observations
Interpolated (1-sec)
to Fill In Gaps

3 Observations
Extrapolated (1-sec)
to Complete Circle

Simulating Coyote Observations for OSSEs

Comparison to Other Data Types Simulated

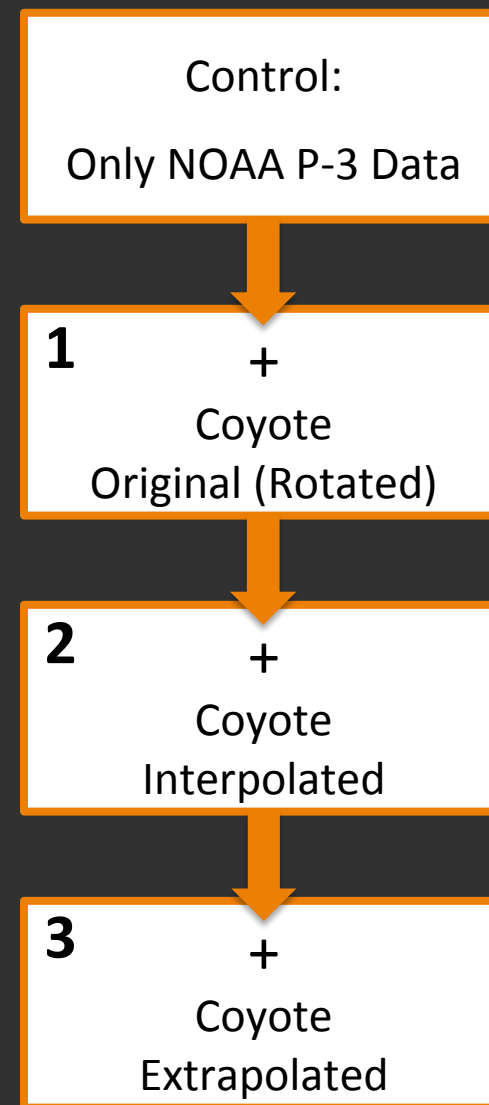
Tail Radar	Dropsonde	Flight Level	SFMR	Coyote
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23,600	1,650	1,100	350	--
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23,650	1,650	1,100	350	1,400
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23,900	1,650	1,100	350	4,800
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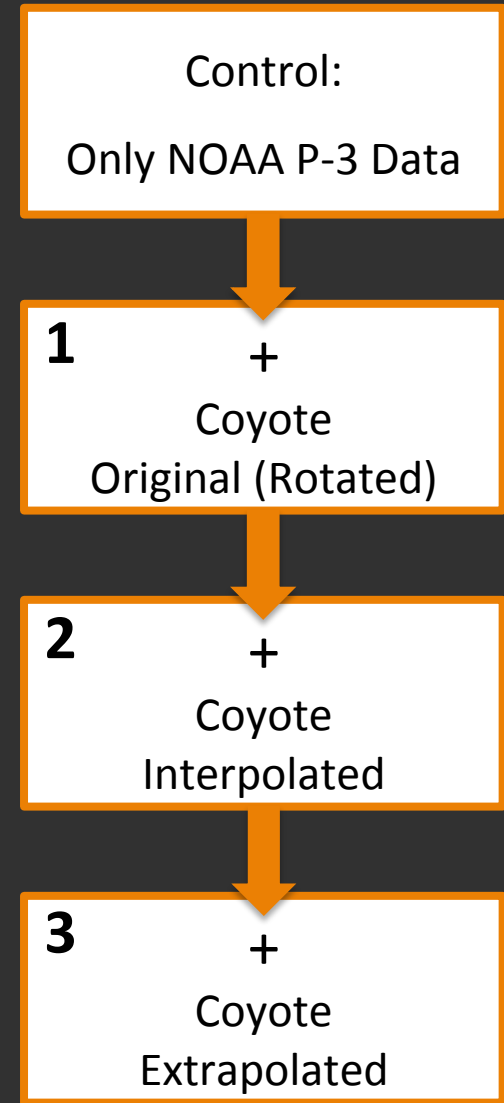
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Simulating Coyote Observations for OSSEs

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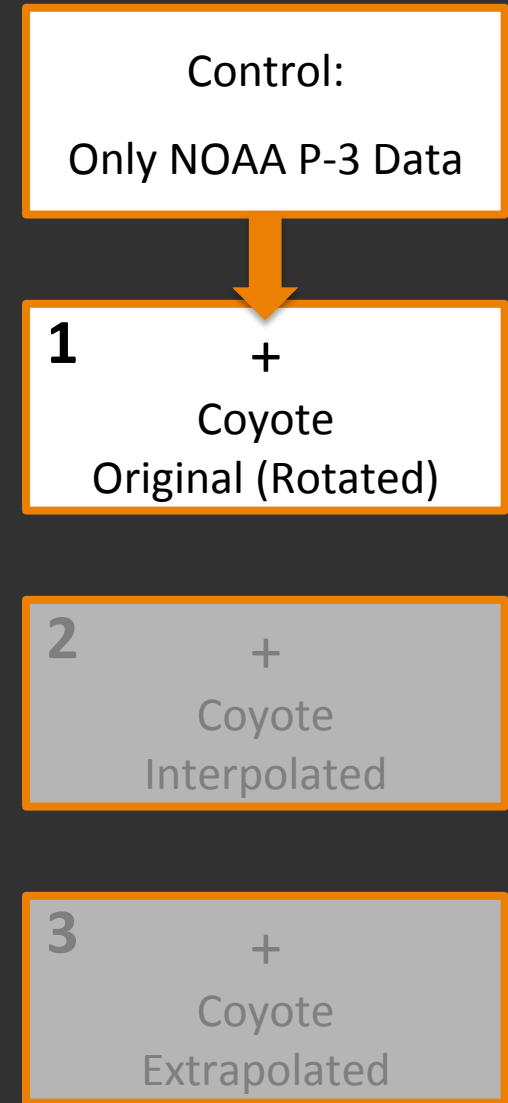
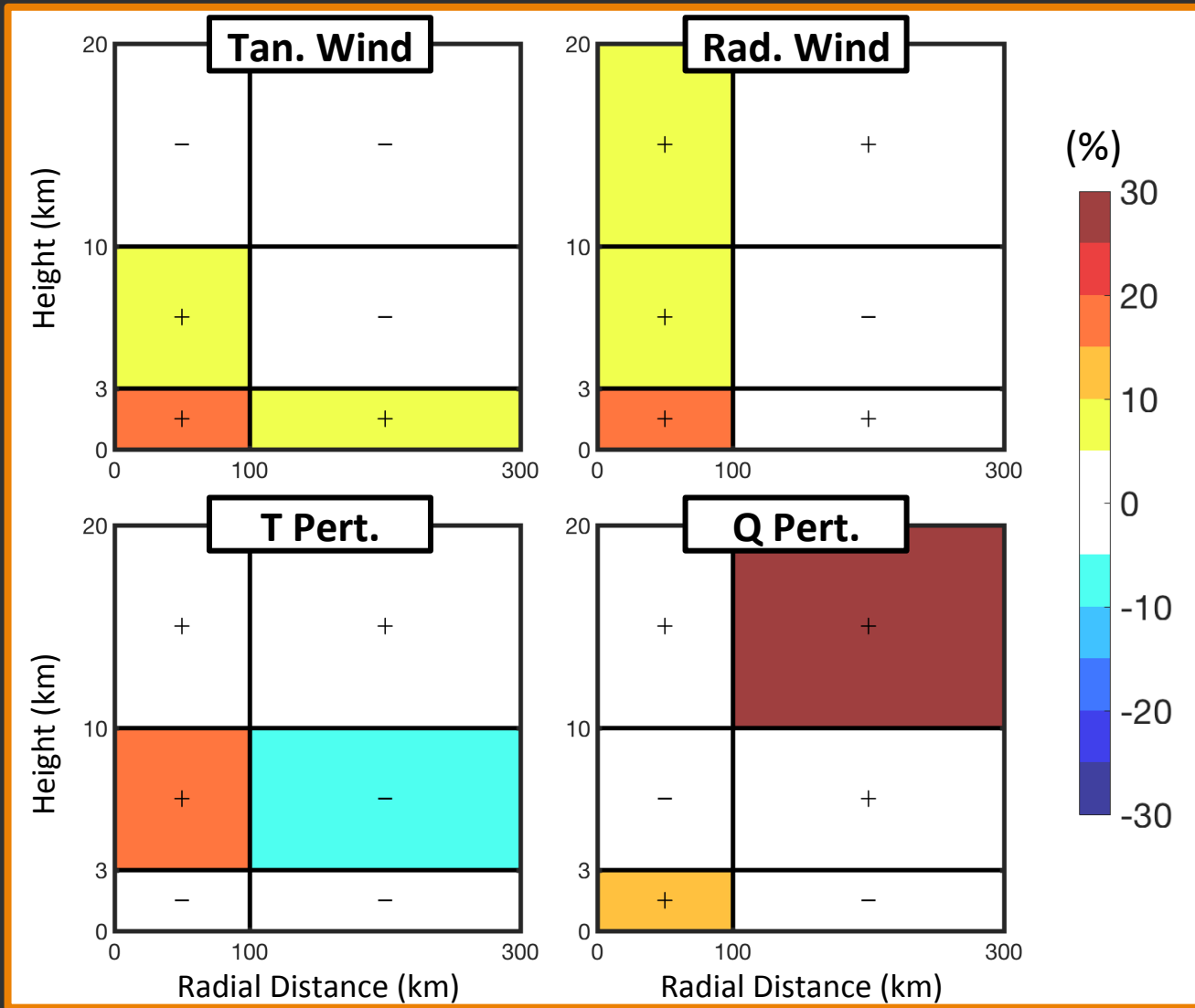
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Results: Impact on Hurricane Structure

Comparison to the Nature Run

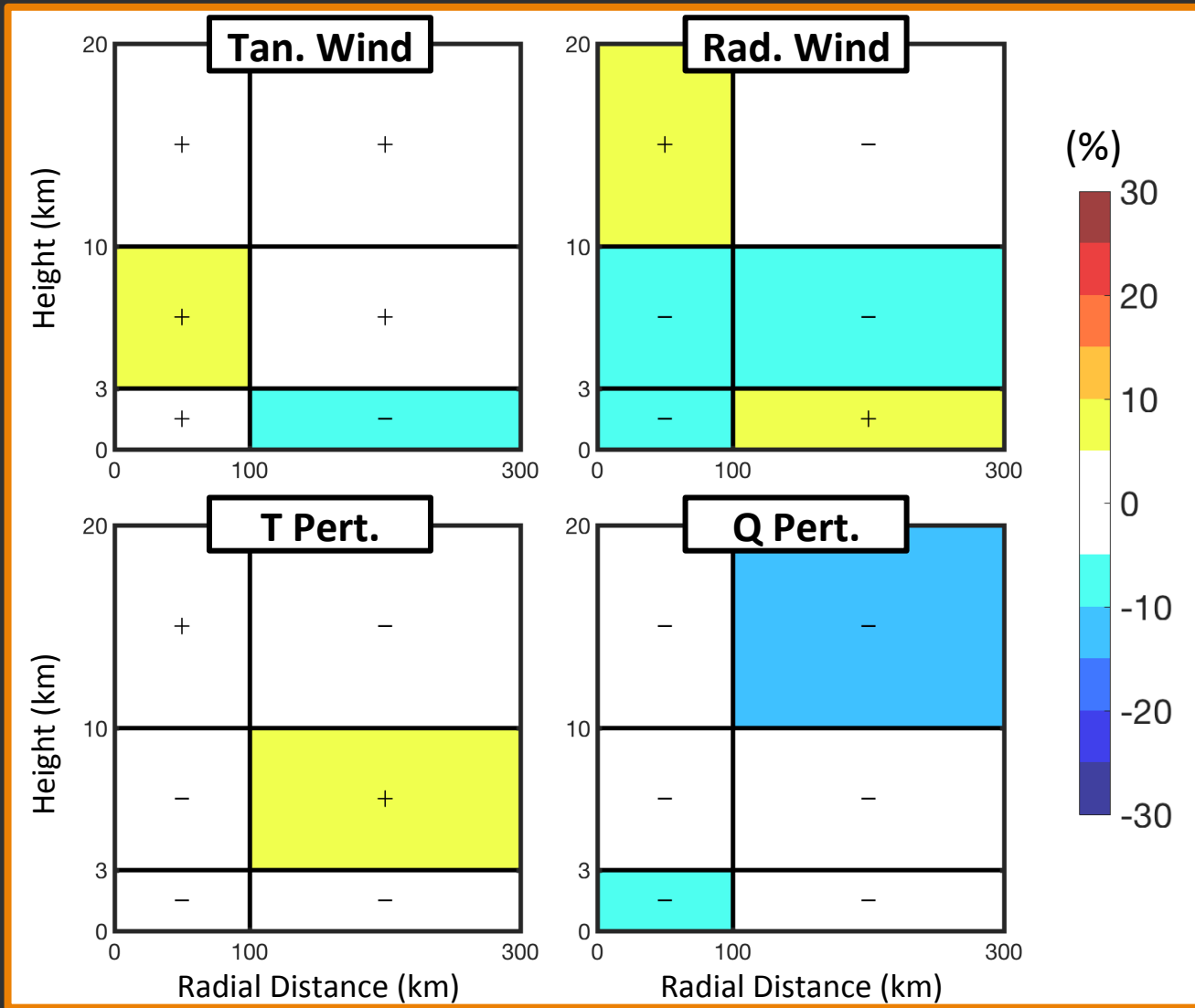
Incremental Improvement (%) in Total Error



Results: Impact on Hurricane Structure

Comparison to the Nature Run

Incremental Improvement (%) in Total Error



Control:
Only NOAA P-3 Data

1 +
Coyote
Original (Rotated)

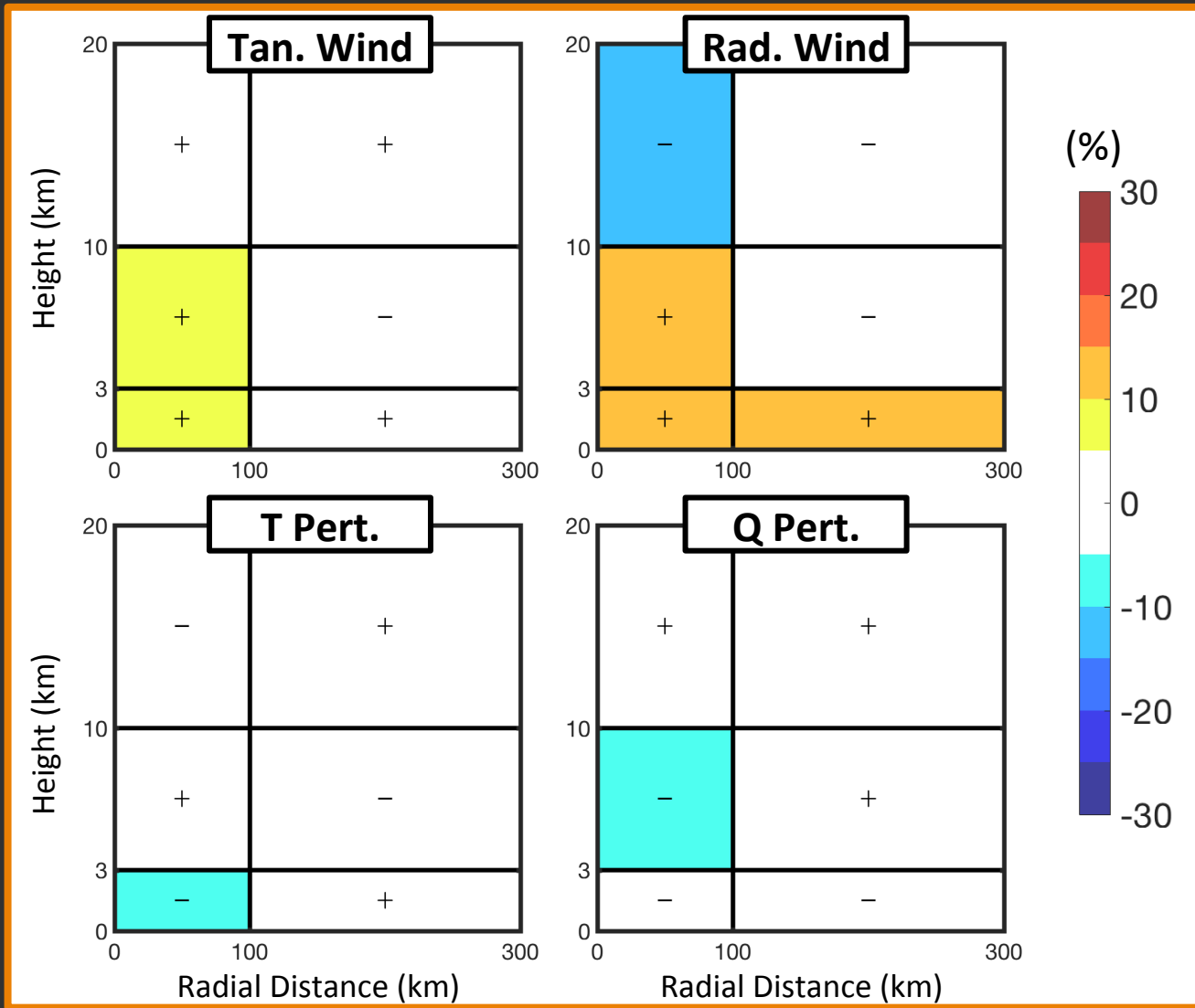
2 +
Coyote
Interpolated

3 +
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Extrapolated

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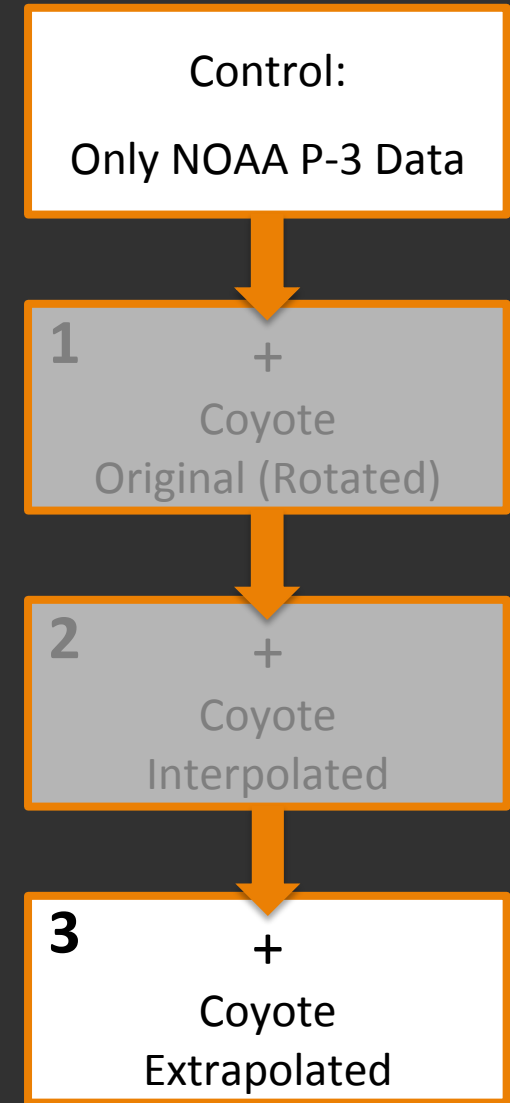
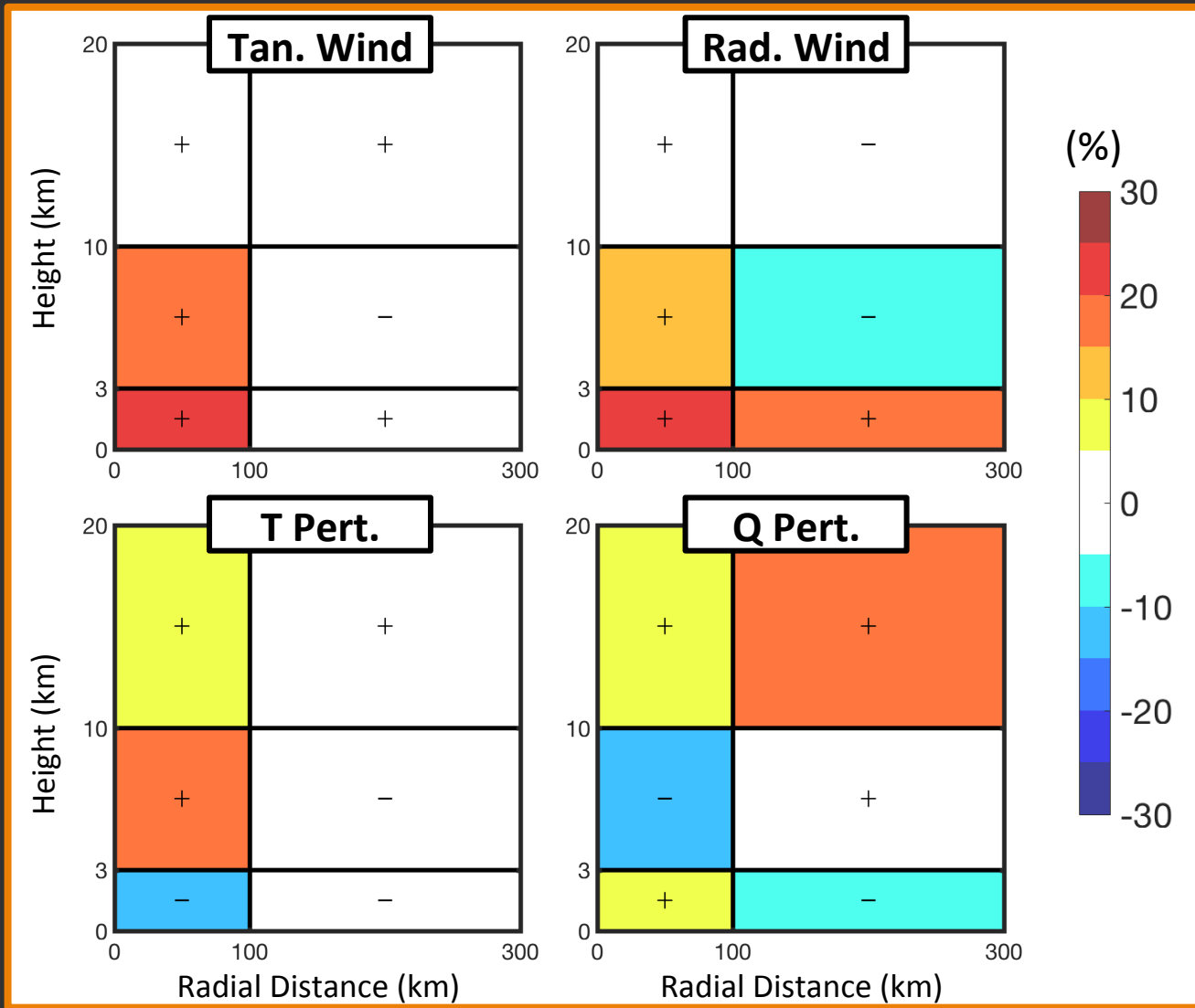
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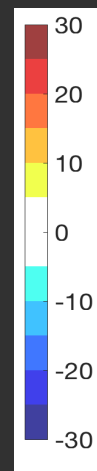
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Simulating Coyote Observations for OSSEs

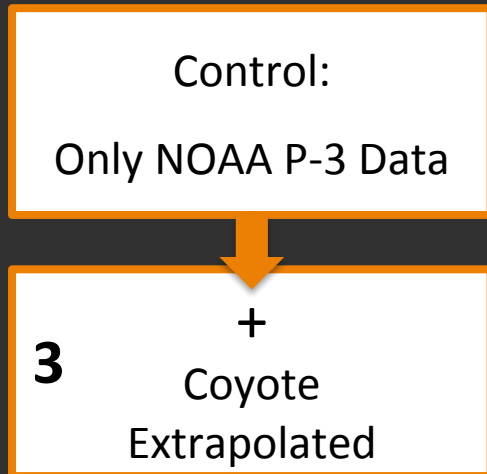
Comparison to the Nature Run

(%)



Improvement in Error (Experiment – Nature Run)

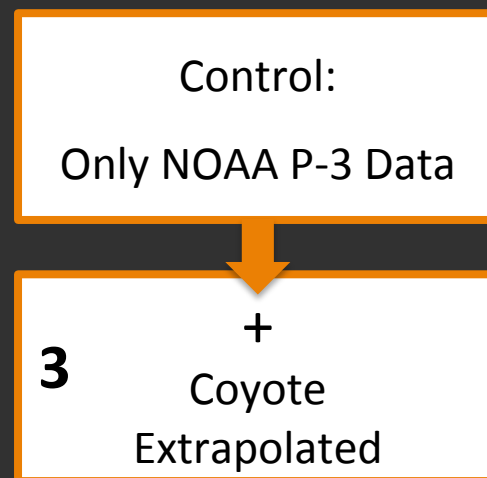
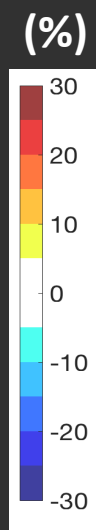
Position	MSLP	Max. Wind	RMW
-1.4 km (-8%)	+1.4 hPa (+6%)	+1.5 m/s (+7%)	+5 km (+24%)



Simulating Coyote Observations for OSSEs

Comparison to the Nature Run

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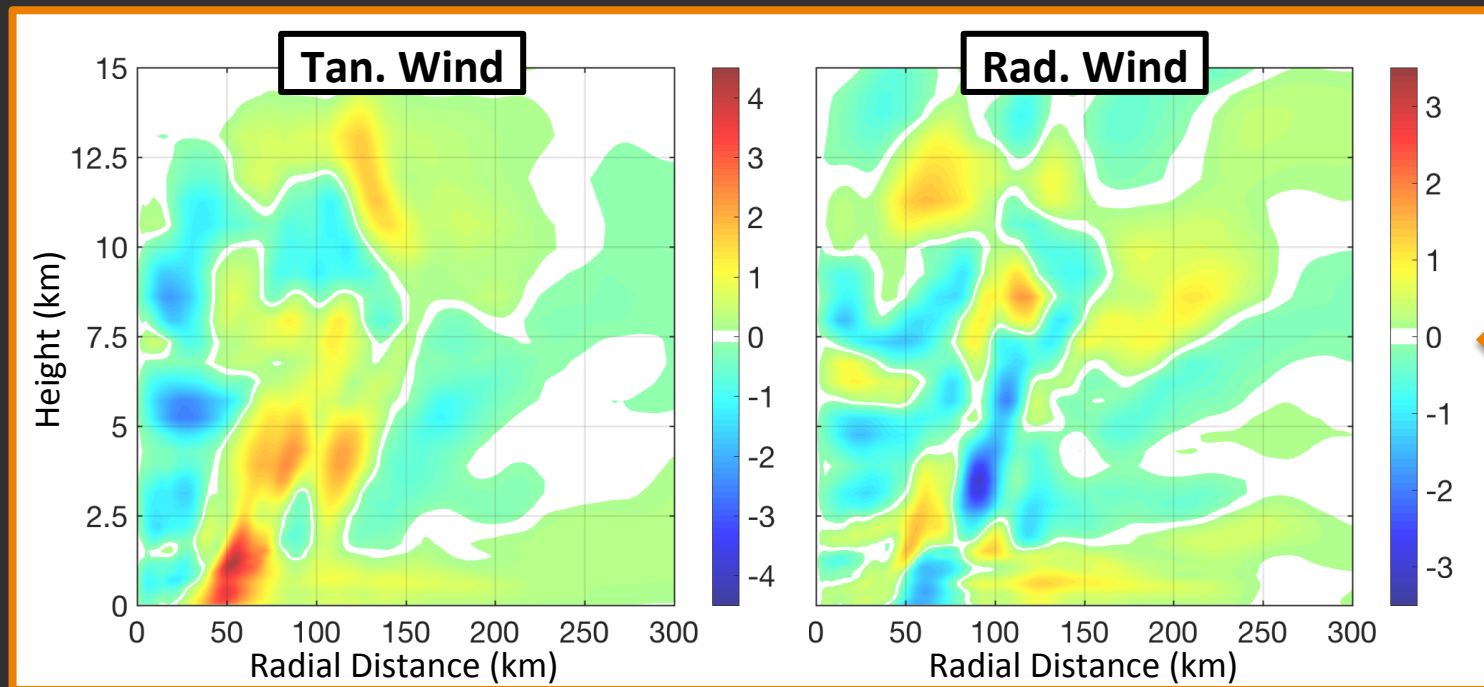
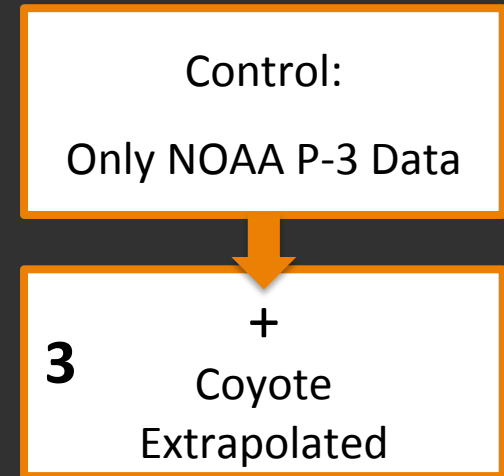
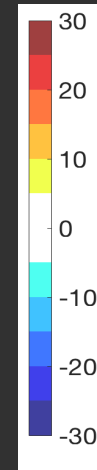
Very Comparable to the Real-Data Experiment

Simulating Coyote Observations for OSSEs

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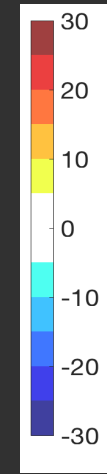
(%)



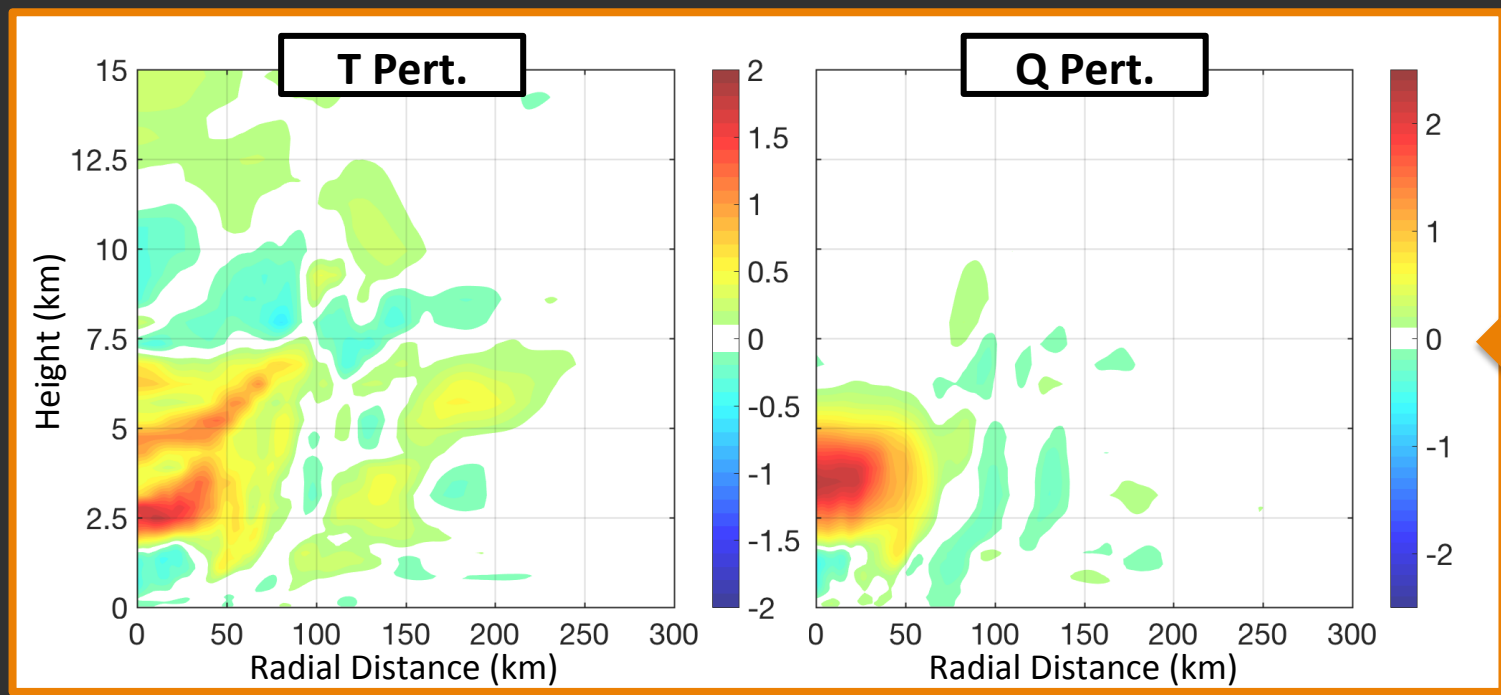
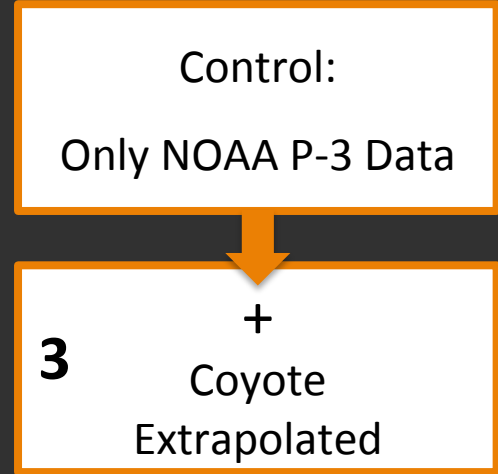
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**Exp 3
minus
Control**

Summary

1. Successful simulation and assimilation of Coyote UAS observations

- This Phase-1 OSSE confirms the findings of the real-data study

2. Small but consistent & meaningful improvements in the kinematic and thermodynamic structures

- Mostly in the low-to-mid levels
- Mostly near the inner core

3. Further optimization in DA may be necessary as # of dense Coyote UAS observations increase in a localized region of the vortex

4. Further research will investigate ways to improve sampling strategies with the Coyote UAS

- Where in the vortex?
- Sampling rate vs sampling duration
- Possibility of simultaneous sampling by multiple aircraft